

Advantech AE Technical Share Document

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Category	□ FAQ■ SOP	Related OS	Linux Operation System
Abstract	How to test CAN port with Advantech CAN card on Linux system?		
	CAN Communication cards / CAN2.0 / CAN2.0A / CAN2.0B / PCI CAN Communication cards		
Keyword	/ PC/104 CAN Communication Modules / PCI/104 CAN Communication Modules / CAN		
	Monitor / CAN Test		
Related Product	PCI-1680U / PCI-1682U / PCL-841 / PCM-3680 / PCM-3680I		

■ Problem Description:

This is a SOP document to describe how to test CAN port with Advantech CAN bus communication card on Linux OS. By connecting the wires correctly, those two CAN port testing can help user to verify the operation of CAN ports by using Advantech Linux CAN example.

■ Brief Solution :

Please refer this steps to test CAN port.

- 1. Please insert CAN card in your PC first. And put Advantech CAN Linux driver in your OS too.
- 2. Connect with Advantech two CAN port, then connect with each CAN_L, CAN_H pin, as Figure 1: (Port A's pin2 to Port B's pin2; Port A's pin7 to Port B's pin7)

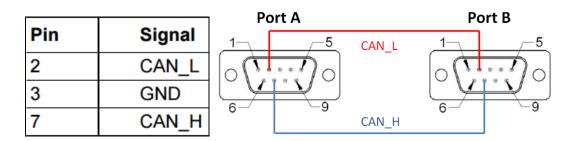


Figure 1. Connect with CAN_L & CAN_H of Port A & Port B.

3. Open one terminal: into example folder, type #make for compiling all example files, as Figure 2.

```
root@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17# cd examples
root@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples# ls
                                        receive-select.c showstat.c
acceptance.c Makefile
                                                                                 transmit-nonblock.c
baud.c
                receive-block.c
                                        selfreception.c
                                                            singlefilter.c
                                                                                 transmit-select.c
can4linux.h
                receive-nonblock.c
                                       send-loctl.c
                                                            transmit-block.c
root@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples# make
gcc -I../can4linux -o baud baud.c -lrt
gcc -I../can4linux -o acceptance acceptance.c -lrt
gcc -I../can4linux -o receive-block receive-block.c -lrt
gcc -I../can4linux -o transmit-block transmit-block.c -lrt
gcc -I../can4linux -o receive-nonblock receive-nonblock.c -lrt
    -I../can4linux -o transmit-nonblock transmit-nonblock.c -lrt
gcc -I../can4linux -o selfreception selfreception.c -lrt
gcc -I../can4linux -o singlefilter singlefilter.c -lrt
gcc -I../can4linux -o transmit-select transmit-select.c -lrt
     I../can4linux -o showstat showstat.c -lrt
  ot@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples#
```

Figure 2. Type #make for CAN example (.c file)



4. After #make successful, please open another new terminal, and into example folder too.

One terminal run "transmit-select" example. (Type: # ./transmit-select can0)

P.S "can0" means transmit CAN data from can PortA.

```
root@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples# clear
root@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples# ls
              Makefile
acceptance
                                   receive-select
                                                     send-loctl.c
                                                                     transmit-block
                                                                                         transmit-select.c
acceptance.c receive-block
                                  receive-select.c showstat
                                                                     transmit-block.c
baud
              receive-block.c
                                  selfreception
                                                    showstat.c
                                                                     transmit-nonblock
baud.c
                                  selfreception.c
                                                    singlefilter
                                                                     transmit-nonblock.c
                                                     singlefilter.c transmit-select
can4linux.h
             receive-nonblock.c send-loctl
root@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples# ./transmit-select can0
using CAN device /dev/can0, got can_fd
write down 5
got one message Error 16
   ERROR PASSIVE
```

Another terminal run "receive-select" example. (Type: # ./receive-select can1) P.S "can1" means receive CAN data from can PortB.

```
ubuntu@ubuntu:~$ sudo su
root@ubuntu:/home/ubuntu# cd Desktop/advcan_source_v2.17/advcan_source_v2.17/examples/
root@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples# ls
acceptance Makefile receive-select send-ioctl.c transmit-block
acceptance Makefile
acceptance.c receive-block
                                                                                                      transmit-select.c
                                                                              transmit-block.
                                       receive-select.c
                                                          showstat
                receive-block.c
                                       selfreception
                                                           showstat.c
                                                                              transmit-nonblock
baud
                                                                              transmit-nonblock.c
                receive-nonblock
                                      selfreception.c
                                                           singlefilter
baud.c
                                                           singlefilter.c transmit-select
                receive-nonblock.c
can4linux.h
                                      send-toctl
root@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples# ./receive-select can1
```

5. If everything works fine, two terminal will be like this:

```
can0 (PortA) -> transmit CAN data
```

```
can1 (PortB) -> receive CAN data
```

```
write down 11585
write down 11570
write down 11580
write down 11580
write down 11595
write down 11595
write down 11600
write down 11605
write down 11635
write down 11640
write down 11640
write down 11645
write down 11645
write down 11645
write down 11645
write down 11650
```

```
count: 9900
count: 10000
count: 10100
count: 10200
count: 10300
count: 18488
count: 10500
count: 10600
count: 10700
count: 10800
count: 18988
count: 11888
count: 11100
count: 11200
count: 11300
count: 11400
count: 11500
count: 11600
```

6. Then please change can port setting; can1 to transmit data, can0 to receive data. Please refer it.

One terminal run "receive-select" example. (Type: # ./ receive-select can0)

```
oot@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples# ls
cceptance
               logfile.txt
                                  receive-nonblock.c
                                                                       singlefilter.c
                                                                                             transmit-select
                                  receive-select
acceptance.c Makefile
                                                        send-ioctl.c
                                                                       transmit-block
                                                                                             transmit-select.c
               receive-block
baud
                                  receive-select.c
                                                        showstat
                                                                       transmit-block.c
baud.c
              receive-block.c
                                                        showstat.c transmit-nonblock singlefilter transmit-nonblock.c
                                  selfreception
                                  selfreception.c
root@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples# ./receive-select cand
```

Another terminal run "transmit-select" example. (Type: # ./ transmit-select can1)

```
oot@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples#
              logfile.txt
                                receive-nonblock.c
                                                                  singlefilter.c
                                                                                       transmit-select
                                                    send-toctl
acceptance
acceptance.c Makefile
                                receive-select
                                                    send-ioctl.c
                                                                  transmit-block
                                                                                       transmit-select.c
             receive-block
                                                                  transmit-block.c
                                receive-select.c
                                                    showstat
                                                    showstat.c
                                                                  transmit-nonblock
baud.c
              receive-block.c
                                selfreception
                                                    singlefilter
                                                                  transmit-nonblock.c
             receive-nonblock selfreception.c
can4linux.h
root@ubuntu:/home/ubuntu/Desktop/advcan_source_v2.17/advcan_source_v2.17/examples# ./transmit-select can1
using CAN device /dev/can1, got can_fd
```

7. As above test result, if both way can work very well with transmit & receive example, that mean these CAN card function is fine.